

Contents

Preface.....	VII
Contents	XIII
Notation.....	XXI
1 Vibration Basics	1
1.1 Introduction	1
1.2 Single Degree of Freedom Systems.....	2
1.2.1 Undamped Free Vibrations	2
1.2.2 Damped Free Vibrations	2
1.2.3 Harmonic Forcing	3
1.2.4 Arbitrary Forcing	4
1.3 Multiple Degree of Freedom Systems	4
1.3.1 Equations of Motion	5
1.3.2 Undamped Free Vibrations	6
1.3.3 Orthogonality of Modes	7
1.3.4 Damped Free Vibrations	7
1.3.5 Harmonically Forced Vibrations, No Damping	7
1.3.6 Harmonically Forced Vibrations, Damping Included	8
1.3.7 General Periodic Forcing	9
1.3.8 Arbitrary Forcing, Transients.....	9
1.4 Continuous Systems	10
1.4.1 Equations of Motion	10
1.4.2 Undamped Free Vibrations	11
1.4.3 Orthogonality of Modes	12
1.4.4 Normal Coordinates	13
1.4.5 Forced Vibrations, No Damping	13
1.4.6 Forced Vibrations, Damping Included.....	14
1.4.7 Rayleigh's Method.....	15
1.4.8 Ritz Method	16
1.5 Energy Methods for Setting Up Equations Of Motion	17
1.5.1 Lagrange's Equations.....	17
1.5.2 Hamilton's Principle	18

1.5.3 From PDEs to ODEs: Mode shape Expansion.....	21
1.5.4 Bypassing PDEs: Using Lagrange's Equations with Continuous Systems	23
1.6 Problems.....	25
2 Eigenvalue Problems of Vibrations And Stability	27
2.1 Introduction	27
2.2 The Algebraic EVP	27
2.2.1 Mathematical Form.....	28
2.2.2 Properties of Eigenvalues and Eigenvectors	28
2.2.3 Methods of Solution.....	29
2.3 The Differential EVP.....	29
2.3.1 Mathematical Form.....	30
2.4 Stability-Related EVPs.....	31
2.4.1 The Clamped-hinged Euler Column	31
2.4.2 The Paradox of Follower-loading	34
2.4.3 Buckling by Gravity.....	35
2.5 Vibration-Related EVPs	36
2.5.1 Axial Vibrations of Straight Rods.....	36
2.5.2 Flexural Vibrations of Beams	37
2.6 Concepts of Differential EVPs	39
2.6.1 Multiplicity	40
2.6.2 Classes of Boundary Conditions: Essential and Suppressible	40
2.6.3 Function-classes: Eigen-, Test-, and Admissible functions	41
2.6.4 Adjointness	41
2.6.5 Definiteness	42
2.6.6 Orthogonality	43
2.6.7 Three Classes of EVPs.....	43
2.6.8 The Rayleigh Quotient.....	43
2.7 Properties of Eigenvalues and Eigenfunctions	44
2.7.1 Real-valueness of Eigenvalues	44
2.7.2 Sign of the Eigenvalues	44
2.7.3 Orthogonality of Eigenfunctions.....	45
2.7.4 Minimum Properties of the Eigenvalues.....	46
2.7.5 The Comparison Theorem	47
2.7.6 The Inclusion Theorem for One-term EVPs	48
2.8 Methods of Solution	49
2.8.1 Closed-form Solutions	50
2.8.2 The Method of Eigenfunction Iteration	50
2.8.3 The Rayleigh–Ritz Method.....	51
2.8.4 The Finite Difference Method	54
2.8.5 Collocation.....	58
2.8.6 Composite EVPs: Dunkerley's and Southwell's Formulas.....	59
2.8.7 Other Methods	60

2.9 Problems	60
3 Nonlinear Vibrations: Classical Local Theory	65
3.1 Introduction	65
3.2 Sources of Nonlinearity	66
3.2.1 Geometrical Nonlinearities	66
3.2.2 Material Nonlinearities	68
3.2.3 Nonlinear Body Forces	69
3.2.4 Physical Configuration Nonlinearities	70
3.3 Main Example: Pendulum with an Oscillating Support	71
3.3.1 Equation of Motion	72
3.4 Qualitative Analysis of the Unforced Response	73
3.4.1 Recasting the Equations into First-order Form	73
3.4.2 The Phase Plane	74
3.4.3 Singular Points	76
3.4.4 Stability of Singular Points	77
3.4.5 On the Behavior of Orbits near Singular Points	79
3.5 Quantitative Analysis	85
3.5.1 Perturbation Methods	85
3.5.2 The Straightforward Expansion	86
3.5.3 The Method of Multiple Scales	88
3.5.4 The Method of Harmonic Balance	92
3.5.5 The Method of Averaging	94
3.6 The Forced Response – Multiple Scales Analysis	96
3.6.1 Posing the Problem	96
3.6.2 Perturbation Equations	97
3.6.3 The Non-resonant Case	99
3.6.4 The Near-resonant Case	100
3.6.5 Stability of Stationary Solutions	102
3.6.6 Discussing Stationary Responses	105
3.7 Externally Excited Duffing Systems	110
3.7.1 Two Physical Examples	111
3.7.2 Primary Resonance, Weak Excitations	116
3.7.3 Non-resonant Hard Excitations	122
3.7.4 Obtaining Forced Responses by Averaging	128
3.8 Concluding Remarks	130
3.9 Problems	130
4 Nonlinear Multiple-DOF Systems: Local Analysis	137
4.1 Introduction	137
4.2 The Autoparametric Vibration Absorber	138
4.2.1 The System	138
4.2.2 First-order Approximate Response	140
4.2.3 Frequency and Force Responses	144

4.2.4 Concluding Remarks on the Vibration Absorber.....	147
4.3 Nonlinear Mode-Coupling of Non-Shallow Arches.....	147
4.3.1 The Model.....	148
4.3.2 Linear Response and Stability	149
4.3.3 Nonlinear Response and Stability	150
4.4 Other Systems Possessing Internal Resonance.....	154
4.5 The Follower-loaded Double Pendulum	155
4.5.1 The Model.....	156
4.5.2 The Zero Solution and its Stability	158
4.5.3 Periodic Solutions.....	160
4.5.4 Non-periodic and Non-zero Static Solutions	164
4.5.5 Summing Up.....	164
4.6 Pendulum with a Sliding Disk.....	165
4.6.1 Introduction.....	165
4.6.2 The System	165
4.6.3 Equations of Motion	166
4.6.4 Inspecting the Equations of Motion.....	167
4.6.5 Seeking Quasi-statical Equilibriums by Averaging	167
4.7 String with a Sliding Pointmass	168
4.7.1 Model System and Equations of Motion.....	169
4.7.2 Illustration of System Behavior	172
4.7.3 Response to Near-resonant Base Excitation	174
4.7.4 Response to Slow Frequency-sweeps	177
4.7.5 Response to Near-Resonant Axial Excitation	179
4.7.6 Non-trivial Effects of Rotary Inertia	182
4.7.7 Summing Up.....	182
4.8 Vibration-Induced Fluid Flow in Pipes	183
4.9 Problems.....	185
5 Bifurcations	189
5.1 Introduction.....	189
5.2 Systems, Bifurcations, and Bifurcation Conditions.....	190
5.2.1 Systems.....	190
5.2.2 Bifurcations.....	190
5.2.3 Bifurcation Conditions: Structural Instability.....	191
5.3 Codimension One Bifurcations of Equilibriums	192
5.3.1 The Pitchfork Bifurcation	192
5.3.2 The Saddle-node Bifurcation	194
5.3.3 The Transcritical Bifurcation.....	195
5.3.4 The Hopf Bifurcation.....	196
5.4 Codimension One Bifurcations for N -Dimensional Systems	197
5.4.1 Saddle-Node Conditions	198
5.4.2 Transcritical and Pitchfork Conditions	199
5.4.3 Hopf Conditions.....	200

5.5 Center Manifold Reduction	201
5.5.1 The Center Manifold Theorem	202
5.5.2 Implications of the Theorem	203
5.5.3 Computing the Center Manifold Reduction	204
5.5.4 An Example	206
5.5.5 Summing up on Center Manifold Reduction	207
5.6 Normal Form Reduction	208
5.7 Bifurcating Periodic Solutions	209
5.8 Grouping Bifurcations According to their Effect	210
5.9 On the Stability of Bifurcations to Perturbations	211
5.9.1 Stability of a Saddle-node Bifurcation	211
5.9.2 Stability of a Supercritical Pitchfork Bifurcation	212
5.10 Summing up on Different Notions of Stability	213
5.11 Examples	215
5.11.1 Midplane Stretching (Duffing's Equation)	215
5.11.2 Pendulum with a Moving Support (Parametric Excitation)	217
5.11.3 The Autoparametric Vibration Absorber	219
5.11.4 The Partially Follower-loaded Double Pendulum	221
5.12 Problems	222
6 Chaotic Vibrations	225
6.1 Introduction	225
6.2 A First Example	227
6.3 Tools for Detecting Chaotic Vibrations	229
6.3.1 Phase Planes	229
6.3.2 Frequency Specters	231
6.3.3 Poincaré Maps	231
6.3.4 Lyapunov Exponents	234
6.3.5 Horizons of Predictability	238
6.3.6 Attractor Dimensions	240
6.3.7 Basins of Attraction	241
6.3.8 Summary on Detecting Tools	242
6.4 Universal Routes to Chaos	242
6.4.1 The Period-doubling Route	243
6.4.2 The Quasiperiodic Route	245
6.4.3 The Transient Route	246
6.4.4 The Intermittency Route	248
6.4.5 Summary on the Routes to Chaos	249
6.5 Tools for Predicting the Onset of Chaos	249
6.5.1 Criteria Related to the Universal Routes of Chaos	249
6.5.2 Searching for Homoclinic Tangles and Smale Horseshoes	251
6.5.3 The Melnikov Criterion	255
6.5.4 Criteria Based on Local Perturbation Analysis	259
6.5.5 Criteria for Conservative Chaos	263

6.6 Mechanical Systems and Chaos	263
6.6.1 The Lorenz System ($D = 3$)	263
6.6.2 Duffing-type Systems ($D = 3$).....	264
6.6.3 Pendulum-type Systems ($D = 3$).....	265
6.6.4 Piecewise Linear Systems ($D \geq 3$).....	267
6.6.5 Coupled Autonomous Systems ($D \geq 4$)	268
6.6.6 Autoparametric Systems ($D \geq 5$)	273
6.6.7 High-order Systems ($D > 5$).....	277
6.6.8 Other Systems	277
6.7 Elastostatical Chaos.....	278
6.8 Spatial and Spatiotemporal Chaos.....	281
6.9 Controlling Chaos	282
6.10 Closing Comments	283
6.11 Problems.....	284
7 Special Effects of High-Frequency Excitation.....	287
7.1 Introduction	287
7.2 The Method of Direct Partition of Motions (MDPM)	288
7.2.1 Outline of the MDPM.....	288
7.2.2 The Concept of Vibrational Force	291
7.2.3 The MDPM Compared to Other Perturbation Approaches.....	291
7.3 Simple Examples.....	292
7.3.1 Pendulum on a Vibrating Support (Stiffening and Biasing)	292
7.3.2 Mass on a Vibrating Plane (Smoothing and Biasing)	297
7.3.3 Brumberg's Pipe (Smoothing and Biasing).....	300
7.4 A Slight but Useful Generalization	302
7.5 A Fairly General Class of Discrete Systems	303
7.5.1 The System	303
7.5.2 Example Functions	304
7.5.3 The Averaged System Governing the 'Slow' Motions	304
7.5.4 Interpretation of Averaged Forcing Terms	307
7.5.5 The Effects.....	308
7.5.6 Stiffening	309
7.5.7 Biasing	312
7.5.8 Smoothing	315
7.6 A General Class of Linear Continuous Systems	318
7.6.1 The Generalized No-Resonance Prediction (GNRP).....	320
7.6.2 The Generalized Analytical Resonance Prediction (GARP).....	322
7.6.3 Example 1: Clamped String With HF Base Excitation.....	324
7.6.4 Example 2: Square Membrane with In-Plane HF Excitation	325
7.7 Specific Systems and Results – Some Examples	327
7.7.1 Using HF Excitation to Quench Friction-Induced Vibrations	327
7.7.2 Displacement due to HF Excitation and Asymmetric Friction	329
7.7.3 Chelomei's Pendulum – Resolving a Paradox.....	329

7.7.4 Stiffening of a Flexible String.....	332
7.8 Concluding Remarks	333
7.9 Problems.....	334
Appendix A – Performing Numerical Simulations	339
A.1 Solving Differential Equations	339
A.2 Computing Chaos-Related Quantities	340
A.3 Interfacing with the ODE-Solver.....	340
A.4 Locating Software on the Internet	343
Appendix B – Major Exercises.....	347
B.1 Tension Control of Rotating Shafts	347
B.1.1 Mathematical Model	348
B.1.2 Eigenvalue Problem, Natural Frequencies and Mode Shapes	348
B.1.3 Discretisations, Choice of Control Law	349
B.1.4 Local Bifurcation Analysis for a Balanced Shaft ($p = me = 0$)	350
B.1.5 Quantitative Analysis of the Controlled System	351
B.1.6 Using a Dither Signal for Open-Loop Control	352
B.1.7 Numerical Analysis of the Controlled System	352
B.1.8 Conclusions	353
B.2 Vibrations of a Spring-Tensioned Beam.....	353
B.2.1 Mathematical Model	353
B.2.2 Eigenvalue Problem, Natural Frequencies and Mode Shapes	355
B.2.3 Discrete Models	355
B.2.4 Local Bifurcation Analysis for the Unloaded System	356
B.2.5 Quantitative Analysis of the Loaded System	356
B.2.6 Numerical Analysis	357
B.2.7 Conclusions	358
B.3 Dynamics of a Microbeam.....	358
B.3.1 System Description	359
B.3.2 Mathematical Model	360
B.3.3 Eigenvalue Problem, Natural Frequencies and Mode Shapes	361
B.3.4 Discrete Models, Mode Shape Expansion.....	361
B.3.5 Local Bifurcation Analysis for the Statically Loaded System.....	362
B.3.6 Quantitative Analysis of the Loaded System	362
B.3.7 Numerical Analysis	363
B.3.8 Conclusions	364
Appendix C – Mathematical Formulas	365
C.1 Formulas Typically Used in Perturbation analysis	365
C.1.1 Complex Numbers.....	365
C.1.2 Powers of Two-Term Sums.....	365
C.1.3 Dirac’s Delta Function (δ).....	366
C.1.4 Averaging Integrals:.....	366

C.1.5 Fourier Series of a Periodic Function.....	366
C.2 Formulas for Stability Analysis	366
C.2.1 The Routh-Hurwitz Criterion	366
C.2.2 Mathieu’s Equation:Stability of the Zero-Solution	367
Appendix D – Vibration Modes and Frequencies for Structural Elements. 371	
D.1 Rods.....	372
D.1.1 Longitudinal Vibrations	372
D.1.2 Torsional Vibrations	372
D.2 Beams	372
D.2.1 Bernoulli-Euler Theory	372
D.2.2 Timoshenko Theory	373
D.3 Rings.....	375
D.3.1 In-Plane Bending	375
D.3.2 Out-of-Plane Bending	376
D.3.3 Extension	376
D.4 Membranes	376
D.4.1 Rectangular Membrane	376
D.4.2 Circular Membrane	377
D.5 Plates	377
D.5.1 Rectangular Plate	377
D.5.2 Circular Plate	378
D.6 Other Structures.....	378
Appendix E– Properties of Engineering Materials 379	
E.1 Friction and Thermal Expansion Coefficients	379
E.2 Density and Elasticity Constants.....	380
References..... 381	
Index..... 393	